Some routing problems on a half-line with release times and deadlines

Alfredo García^{*1} and Javier Tejel^{*1}

¹Departamento de Métodos Estadísticos and IUMA, Universidad de Zaragoza, Spain

The following problem is studied in [1, 3]. Let N = $\{1, 2, \ldots, n\}$ be a set of customers located on the real half-line \mathbb{R}^+ and let D be a depot located at x = 0. The distance (and also the travel time) from customer *i* to the depot is denoted by τ_i . A vehicle has to deliver goods from the depot to the customers. Each customer places an order to the depot and this order is associated with a time window $[r_i, l_i]$, with $l_i = r_i + S - \tau_i$. The release time r_i specifies the earliest possible time the vehicle can depart the depot to deliver at i. S can be seen as a service guarantee such that customer icannot be served after $r_i + S$. Thus, $r_i + S - \tau_i$ is the latest dispatch time for customer i. For example, we can think of a restaurant delivering meals at home as a depot, the release time of an order (a customer ordering for a meal) as the time that the order can be dispatched from the restaurant after preparing the meal, and Sas the time in which the restaurant guaranties that the order will be delivered.

The problem analyzed in [3] is determining the minimum possible completion time c^* of a schedule of delivery routes that can be executed by a single driver, each starting and ending at the depot, such that each order *i* is dispatched at or after r_i and delivered at or before $r_i + S$. Any feasible solution to the problem will consist of a set of k routes, visiting a subset of customers in each route. Assuming that the customers are ordered according to their release times, that is, $r_1 \leq \ldots \leq r_n$, it is proved in [3] that there is always an optimal delivery schedule with noninterlacing routes, where two routes K_1 and K_2 , with $\min\{i \mid i \in K_1\} < \min\{j \mid j \in K_2\}$, are non-interlacing if and only if $\max\{r_i | i \in K_1\} < \min\{r_i | j \in K_2\}$. As a consequence, in any delivery schedule with noninterlacing routes, the customers visited in any route have consecutive release times.

Geometrically, one can imagine the set of customers as a set of n horizontal segments s_1, \ldots, s_n such that the y-coordinate of s_i is τ_i and the x-coordinates of the endpoints of s_i are r_i and l_i , respectively. The abscissa axis represents time. For instance, Figure 1 shows a set of eight customers and a feasible schedule (in red), consisting of three routes, K_1, K_2 and K_3 , to



Figure 1: A feasible schedule to serve eight customers.

serve the eight customers. After waiting at the depot, K_1 starts at r_2 , dispatches orders 2, 1 and 3, and ends at $r_2 + 2\tau_3$. K_2 starts at $r_2 + 2\tau_3$, dispatches orders 4 and 5, and ends at $r_2 + 2\tau_3 + 2\tau_5$. Finally, after waiting again at the depot for a while, K_3 starts at r_8 , dispatches orders 8, 7 and 6, and ends at $r_8 + 2\tau_6$.

Let c(i) be the minimum completion time of a noninterlacing schedule serving orders $\{1, \ldots, i\}$, or ∞ if it is not possible to serve $\{1, \ldots, i\}$ feasibly with a single server. Thus, c^* will be given by c(n). Defining c(0) = 0, the following recurrence [3] allows one to compute c(i), for $i = 1, \ldots, n$:

$$c(i) = \min_{0 \le j < i} \left\{ \max\{c(j), r_i\} + 2 \max_{j < k \le i} \{\tau_k\} \mid \max\{c(j), r_i\} \le \min_{j < k \le i} \{l_k\} \right\}$$

In this talk, we will show how to solve this recurrence in $O(n \log n)$ time, improving the $O(n^2)$ algorithm given in [3]. In addition, using the algorithm described in [2], if $S = \infty$, that is, there are no deadlines, then the previous recurrence can be solved in O(n) time, improving the $O(n^2)$ algorithm provided in [3].

References

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^{*}Emails: {olaverri, jtejel}@unizar.es. Research supported by project PID2019-104129GB-I00 / AEI / 10.13039/501100011033 of the Spanish Ministry of Science and Innovation, and by Gobierno de Aragón project E41-23R.